

THE ELECTRIC WORK CLASS ROV EMPOWERING ECO-RESPONSIBILITY

The latest addition to Saab's underwater portfolio, the Seaeye SR20 eWROV, is an IMCA Class III B ROV system. Electrification is the key to improved performance, and the SR20 takes electric underwater vehicle capabilities to the next level. SR20 is the world's most capable all-electric, work-class underwater robot. With overall power and performance exceeding that of a 200 HP hydraulic equivalent, SR20 delivers maximum capability across all markets and applications, including survey, IMR, construction, drill support and decommissioning. This combined with a compact footprint and increased levels of efficiency reinforces SR20's position as best in class.



Advanced Control

The SR20 provides the user with a number of control options. A responsive and flexible control system provides real-time control via a traditional manual joystick, utilising telemetry data delivered in simple human readable formats. Connection is simplified by use of standard web technologies allowing for low-latency control of the ROV, either via joystick commands or nudge commands.

Environmentally Considerate

The goal of carbon neutrality is a growing focus among the global community, and the SR20 has been designed with eco-responsibility in mind. As well as being more efficient, electric systems use limited fluid making the SR20 significantly more environmentally friendly than equivalent hydraulic work-class systems.

Reliable

SR20 is a new generation of robot, designed from the outset with the ability to persist at sea for long durations without human intervention. With new levels of reliability and low maintenance, the SR20 has unprecedented levels of intelligence, equipment and performance.

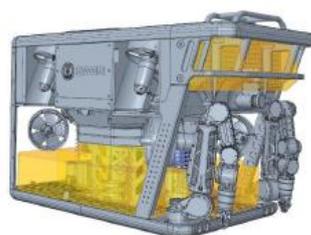
World leader in electric underwater robotics

System Overview

- The SR20 introduces new standards of reliability and low maintenance, combined with high levels of automation and autonomy. These advancements enable deployment from smaller, minimally crewed vessels, further reducing the CO₂ footprint and improving health and safety risks.
- The distributed hardware and software principles at the core of the SR20 were pioneered by Saab. This Ethernet-based architecture forms an intelligent network of configurable hardware and software modules, delivering advanced underwater robotic solutions. The modular system provides real-time control and feedback across every subsystem, making the SR20 ideally suited for increasingly remote and autonomous operations. The comprehensive common technology ecosystem simplifies operation, training, and maintenance, while the expandable, future-proof architecture ensures long-term adaptability.
- Low latency IP camera operation is core to the SR20's Ethernet-architecture design. Its video routing system uses cameras configured to send multicast Ethernet traffic via managed layer 3 switches. This allows multiple receiving devices to send and receive video streams, with no traffic duplication or additional hardware. This multicast approach minimises elements in the video system, and enhances flexibility in video distribution. Precision Time Protocol (PTP) synchronises video devices, achieving nanosecond accuracy and compensating for network latency and jitter, particularly benefiting remote, onshore-operators managing video and telemetry data.
- An open, low latency, API control system is the key to smoothing the transition from today's manually controlled ROVs with auto-functions through to smart robotics with full autonomy. Designed to be part of a system of systems SR20 can be simply integrated into the customer ecosystem; augmented, and upgraded with best of breed sensors and software to deliver increasing levels of autonomy and automation as technology evolves and matures through time. The open API enables re-use of existing control systems, and simple integration with third party smart solutions e.g. Eiva.
- State-of-the-art DC power transmission providing three HVDC outputs are exported from the surface unit: Two of these outputs are utilised on the vehicle with the third being used for the TMS. Each output is individually monitoring and switched, allowing isolation of either Vehicle vs TMS, or even within the Vehicle partition. The system offers full diagnostics, monitoring and protection for the system: including input power monitoring and conditioning, output monitoring and individual leg switching. All local controls are mirrored into the digital control system.
- Electric thrusters are central to the electrification of work ROVs. Each generating 520 kgf, the SR20's efficiency far exceeds that of hydraulic systems, delivering superior acceleration, braking, and reversal performance.
- Electric manipulators play a pivotal role in the electrification ethos of work ROVs, with significant advantages over hydraulic alternatives: more precise positioning, enhanced dexterity, improved reliability—key for autonomous and resident applications. Featuring an advanced control system with an open interface, work ROV manipulators support both manual and automated operations. Highly accurate, modular electric joints enhance arm control, enable advanced path planning solutions, and actuator re-use.
- In its standard configuration, the SR20 offers approximately 1,350 litres of available payload volume, which increases to 1,550 litres when the hydraulics module and valve pack are removed.
- The extremely rugged chassis, constructed from polymer, aluminium, and stainless steel, is designed to maximise water flow through the ROV. Optimised materials and design achieve a lightweight yet robust chassis providing excellent strength and stiffness. The chassis includes rigid mountings for skids, tools, and sensors, and is engineered for repeated and prolonged submergence in marine environments, offering exceptional corrosion resistance throughout its design life.
- The SR20 is available as a free-swimming ROV or with a Top-Hat Tether Management System (TMS).



Best in class SM14
Electric Thruster



Generous 1550 litres of
payload space

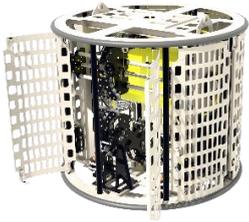


Ground breaking eM1-7
Electric Manipulator

Technical Specifications

General		Optional Hydraulic Power	
System Power Requirements	Configurable for 3-phase, 440 or 690 VAC 50/60Hz	HPU Pressure	207 bar
Depth Rating	3000m (4000m option)	HPU Flow	160 l/min
Dimensions (LxWxH)	2850 mm x 1800 mm x 1900 mm	Hyd. Power	55 kW
Standard Launch Weight	Approximately 3500 kg	Valve pack	12 Station comprising; <ul style="list-style-type: none"> • Four 12lpm NG4 mini-proportional valves • Five 30lpm NG4 mini solenoid valves • One 32lpm NG6 proportional valve • One 65lpm NG6 solenoid valve • One 160lpm high-flow logic element • Pressure gallery proportional pressure control • Multiple P&T connections for circuit expansion
Payload	>250 kg	Fluid	Shell Panolin synthetic biodegradable Mineral in accordance with DIN51524 parts 2 & 3
Mechanical		Video and Electrical Interfaces	
Through Frame Lift	3000 kg	Data Link	20Gb/S Ethernet on Single Mode Fibre Spare Fibre at ROV JB for Survey/Video
Performance		Sensor Interfaces	<ul style="list-style-type: none"> • 32 x software configurable ports (GB Ethernet, RS232/485, TTL/PPS), switchable 24/48 VDC • Optional additional 16 x client configurable (Ethernet & serial), switchable 24/48 VDC
Forward Speed	> 4 knots	Video Interface	HD IP
Lateral Speed	3 knots	High Power tooling	>30kW @ 600VDC
Vertical Speed	2 knots	Manipulators	
Thrust Forward	1200 kgf	Dual Saab Seaeye 7 function electric eM1-7 manipulators	
Thrust Reverse	1200 kgf	Tether Management System (TMS)	
Thrust Lateral	1200 kgf	Type	Top hat
Thrust Vertical	1200 kgf	Drive	All electric
All electric Propulsion		Dimensions (D x H)	2.4 m x 2.4 m
Thrusters	8 x Saab Seaeye SM14	Weight	3,000 kg
Propeller Diameter	390 mm	Depth rating	4,000m
Thrust	520 kgf	Tether capacity	850m (28mm tether)
Standard Instruments			
Pan and Tilt	2 x electric P&T units		
Lighting	8 x LED lamps, dimmable, 10K lumens each		
Depth Sensor	+/-0.01% FS accuracy		
INS	Navigation or survey grade		
DVL	Navigation or survey grade, close coupled with INS		

Deployment Systems and Control Cabins



All electric Top Hat Tether Management System with an 850m capacity of 28mm tether, fitted with Latch Status, Line Out, Motion Reference Unit (MRU) and depth sensor. Options include USBL, altimeter and water current sensor, and additional downward looking light and camera.



A-Frame Safe Area Launch and Recovery System (LARS) with 3300m umbilical (34mm) winch capacity. Active Heave Compensation (AHC) and Zone II upgrade options are available. Optional folding platform for additional work space.



Safe Area 20ft Control Cabin fitted with electric power distribution panels, lighting, air conditioning, heating and 19 inch racks. A Zone II upgrade option is available.